



### 905nm Laser Rangefinder Module 1200A1

Model:LRF1200A2

#### **₹** OVERVIEW



LRF1200A2 laser ranging module is a new lightweight and compact ranging module, operating at a wavelength of 905nm. The maximum range of the product is ≥1200m, using a UART-TTL interface and supporting test software, which is convenient for users to further develop. It has the characteristics of small size, light weight and reliable performance. It can be used in aviation, communications, geology, police, outdoor sports and other occasions.

#### **₹** TECHNICAL SPECIFICATIONS

| Project                          | Technical data                                      |  |  |  |  |  |
|----------------------------------|---|--|--|--|--|--|
| Model                            | LRF1200A2   |  |  |  |  |  |
| Laser Wavelength                 | 905nm   |  |  |  |  |  |
| Eye Safety                       | Class 1   |  |  |  |  |  |
| Divergence Angle                 | ≤10mrad   |  |  |  |  |  |
| Display accuracy                 | 0.1m  |  |  |  |  |  |
| Launch Lens Diameter             | Ф6.6mm  |  |  |  |  |  |
| Receiver Lens Diameter           | Ф18mm   |  |  |  |  |  |
| Measuring Range (3m x 3m Target) | ≥5~1200m  |  |  |  |  |  |
| Ranging Accuracy                 | ±1m   |  |  |  |  |  |
| Display Accuracy                 | 0.1m  |  |  |  |  |  |
| Ranging Frequency                | 1~3Hz   |  |  |  |  |  |
| Accurately measuring probability | ≥98%  |  |  |  |  |  |
| Start Time                       | ≤500ms  |  |  |  |  |  |
| Data Interface                   | UART (TTL_3.3V)                                     |  |  |  |  |  |
| Supply Voltage                   | 3.3+/-0.1V  |  |  |  |  |  |
| Standby Power Consumption        | ≤300mW  |  |  |  |  |  |
| Work Power Consumption           | ≤800mW  |  |  |  |  |  |
| Weight                           | ≤20g  |  |  |  |  |  |
| Dimention                        | Ф25mm×40mm  |  |  |  |  |  |
| Operation Temperature            | -20∼+55°C   |  |  |  |  |  |
| Storage Temperature              | -55~+65°C   |  |  |  |  |  |
| Impact Resistance                | 1200g, 1ms  |  |  |  |  |  |
| Anti-vibration                   | 1000g/ms (10 times/s in the optical axis direction) |  |  |  |  |  |
| Dependability                    | MTBF≥1500 h   |  |  |  |  |  |

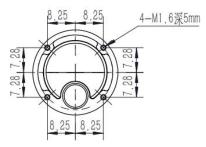


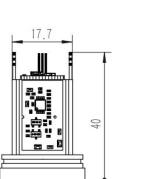


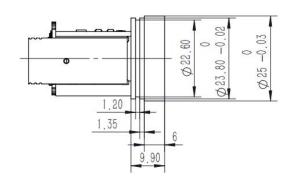
| Protection Class                    | IP67(Head piece)  |
|-------------------------------------|---|
| ESD Class                           | (Lens position) Contact discharge 6kV Air discharge 8kV |
| Electromagnetic Compatibility (EMC) | CE/FCC Certification                                    |
| Eco-friendly                        | RoHS2.0   |

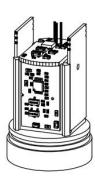
- In this mode, the device consumes minimal power. The MCU is in an off state and does not respond to any commands.
- When a measurement is needed, pull the enable pin low to switch the device into normal working mode and automatically perform one measurement.
- After the measurement is complete, pull the enable pin high to return the device to low-power mode, with power consumption below 3mW.

## **₹** MECHANICAL DIMENSION( mm)









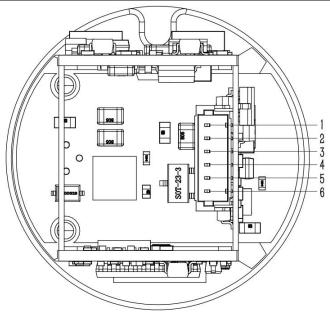
#### **₹** ELECTRICAL INTERFACE

User Electrical Interface: UART (TTL 3.3V)

Connector Model No.: FWF08002-S06B13W5M, wire sequence and specific definitions are shown below:







| Pin | Definition   | Illustrate                         |
|-----|--------------|------------------------------------|
| 1   | GND          | Earth (wire)                       |
| 2   | Power supply | 3.3V DC power supply               |
| 3   | NC           | Empty pin                          |
| 4   | TTL_TXD      | Serial transmitter, TTL level 3.3V |
| 5   | TTL_RXD      | Serial Receiver, TTL Level 3.3V    |
| 6   | Enable Pin   | low level power on                 |

# **REPORT NOT COLUMN TERROR DE COMMUNICATION PROTOCOL**

Communication mode: using serial communication mode

Baud rate: 115200 (default)

Data Bits: 8 Bits

Length of a frame: 8 bytes

|       |                | DATA P         |               |    |    |    |    |  |
|-------|----------------|----------------|---------------|----|----|----|----|--|
|       | Frame header H | Frame header L | Function word | D1 | D2 | D3 | D4 | Calibration                                  |
| Send  | 55             | AA             |               |    |    |    |    | SUM(function word<br>+DATA1++DATA4)          |
| Reply | 55             | AA             |               |    |    |    |    | SUM(frame header H + frame header L ++DATA4) |

|                | MEASUREMENT INSTRUCTION |  |   |    |          |             |       |       |           |  |  |
|----------------|-------------------------|--|---|----|----------|-------------|-------|-------|-----------|--|--|
|                | Send                    | 55   | AA  | 88 | FF       | FF          | FF    | FF    | SUM[3: 7] |  |  |
|                | Seliu                   |  |   |    | 55 AA 88 | FF FF FF FF | 84    |       |           |  |  |
| Single ranging |                         | 55   | AA  | 88 | STA      | FF          | DIS_H | DIS_L | SUM[1: 7] |  |  |
|                | Reply                   | DIS_H: high  | easurement failure; STA = 1: The measurement was successful the bytes of the measured result; DIS_L: The lower bytes of the measurement result the same returned in hexadecimal, and all data results are output by multiplying the real data by 10 |    |          |             |       |       |           |  |  |
|                | 1                       | 55   | AA  | 89 | FF       | FF          | FF    | FF    | SUM[3: 7] |  |  |
|                | send                    |  | 55 AA 89 FF FF FF 85  |    |          |             |       |       |           |  |  |
| Continuous     |                         | 55   | AA  | 88 | STA      | FF          | DIS_H | DIS_L | SUM[1: 7] |  |  |
| ranging        | Reply                   | STA = 0 measurement failure; STA = 1: The measurement was successful DIS_H: high bytes of the measured result; DIS_L: The lower bytes of the measurement result Data returns are returned in hexadecimal, and all data results are output by multiplying the real data by 10 |   |    |          |             |       |       |           |  |  |
|                | send                    | 55   | AA  | 8E | FF       | FF          | FF    | FF    | SUM[3: 7] |  |  |
| Stop ranging   | SCHU                    |  |   |    | 55 AA 8E | FF FF FF FF | 8A    |       |           |  |  |
|                | Reply                   | 55   | AA  | 8E | STA      | FF          | FF    | FF    | SUM[1: 7] |  |  |





|             |       | STA= 0 closes multiple measurement failures; STA = 1 closes multiple measurements successfully              |   |    |     |    |       |       |           |  |
|-------------|-------|---|---|----|-----|----|-------|-------|-----------|--|
|             | gond  | 55  | AA  | 8A | FF  | FF | FF    | FF    | SUM[3: 7] |  |
|             | send  | 55 AA 8A FF FF FF 86  |   |    |     |    |       |       |           |  |
| Angular     |       | 55  | AA  | 8A | STA | FF | ANG_H | ANG_L | SUM[1: 7] |  |
| measurement | Reply | STA= 0 Measurement failure; STA= 1: Measurement success   |   |    |     |    |       |       |           |  |
|             | Керту | ANG_H: Measurement result high byte; ANG_L: Measurement result low byte, data return to hexadecimal return, |   |    |     |    |       |       |           |  |
|             |       | all data resu   | all data results will be the real data multiplied by 10 output, only in the movement with an angle sensor effective |    |     |    |       |       |           |  |

| POWER-ON SELF-TEST  |       |             |   |    |     |    |    |         |           |
|---|-------|-------------|---|----|-----|----|----|---------|-----------|
| Self-test   |       | 55          | AA  | 80 | STA | 00 | 00 | ErrCode | SUM[1: 7] |
| information   | Reply | STA= 0 Boot | STA= 0 Boot initialization failed, ErrCode is the error code; |    |     |    |    |         |           |
| STA= 1 Boot initialization success. By default, initialization success does not reply to such messages. |       |             |   |    |     |    |    |         |           |

|                   |       | SET   | TING UP TH              | E SYSTEM         |                 |        |    |    |           |  |
|-------------------|-------|---|-------------------------|------------------|-----------------|--------|----|----|-----------|--|
|                   |       | 55  | AA                      | ТҮРЕ             | FF              | FF     | FF | FF | SUM[3: 7] |  |
| Baud rate         | Send  | TYPE = 01 sets the baud rate to 9600 bps  TYPE = 02 Set the baud rate to 14400 bps  TYPE = 03 Set the baud rate to 19200 bps  TYPE = 04 Set the baud rate to 38400bps  TYPE = 05 Set the baud rate to 56000 BPS  TYPE = 06 Set the baud rate to 57600bps  TYPE = 07 Set the baud rate to 115200bps  TYPE = 08 Set the baud rate to 128000bps  TYPE = 09 Set the baud rate to 230400bps  TYPE = 09 Set the baud rate to 230400bps  The baud rate does not change immediately after it is set and only takes effect after a restart |                         |                  |                 |        |    |    |           |  |
|                   | Reply | 55  | AA                      | TYPE             | STA             | FF     | FF | FF | SUM[1: 7] |  |
|                   | перту | STA = 0 setting failure; STA = 1 is set successfully  |                         |                  |                 |        |    |    |           |  |
| - 1               | C 1   | 55  | AA                      | 70               | AB              | CD     | 00 | 00 | SUM[3: 7] |  |
| External          | Send  | 55 AA 70 AB CD 00 00 E8   |                         |                  |                 |        |    |    |           |  |
| circuit<br>enable | D 1   | 55  | AA                      | 70               | STA             | 00     | 00 | 00 | SUM[1: 7] |  |
| Chable            | Reply | STA = 0   | , enable failure        | e; STA = 1, ena  | bling success   | •      | •  |    |           |  |
|                   |       | 55  | AA                      | 71               | AB              | CD     | 00 | 00 | SUM[3: 7] |  |
|                   |       |   | 55 AA 71 AB CD 00 00 E9 |                  |                 |        |    |    |           |  |
|                   |       | 55  | AA                      | 71               | STA             | 00     | 00 | 00 | SUM[1: 7] |  |
|                   |       | STA = 0, dis  | able failure; If        | STA = 1, it is d | isabled success | sfully | •  |    | •         |  |

|            | <b>ErrCode</b>                        |         |
|------------|---------------------------------------|---------|
| Error code | Description                           | Remarks |
| 0x00       | No echo signal was received           |         |
| 0x16       | Out of range: below the minimum range |         |
| 0x18       | No echo signal was received           |         |
| 0x00~0x07  | Hardware error                        |         |

#### **₹** SECONDARY LOW- POWER MODE

- In this mode, the device's power consumption is reduced, and the MCU is in standby mode, capable of responding to other commands.
- > Send the "External Circuit Disabled" command to switch the device into secondary low-power mode.
- When a measurement is needed, simply send a "Measurement" related command to automatically switch the device into normal working mode for measurement.
- Alternatively, send the "External Circuit Enabled" command to switch the device into normal working mode independently.

#### **₹** NOTES

- 1. The verification content for sending and receiving may differ, so please pay attention to discrimination.
- 2. The checksum is the lower eight bits of the sum of the bytes requiring verification.
- 3. All data is transmitted and received in hexadecimal.